

The Cross Product

Def The 2×2 (read "2 by 2") determinant is computed

$$\begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

The 3×3 determinant is computed

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

↑ note this minus sign

This is called "co-factor expansion about the first row".

Def For two vectors $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ in V_3 , we define the cross product of \vec{a} and \vec{b} to be

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \hat{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \hat{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \hat{k}$$

*The cross product is a vector in V_3 *

$$Ex \quad \vec{a} = 2\hat{i} - \hat{j} + 3\hat{k}, \quad \vec{b} = \hat{i} + 3\hat{j} + 5\hat{k}$$

$$\begin{aligned} \vec{a} \times \vec{b} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -1 & 3 \\ 1 & 3 & 5 \end{vmatrix} = \begin{vmatrix} -1 & 3 \\ 3 & 5 \end{vmatrix} \hat{i} - \begin{vmatrix} 2 & 3 \\ 1 & 5 \end{vmatrix} \hat{j} + \begin{vmatrix} 2 & -1 \\ 1 & 3 \end{vmatrix} \hat{k} \\ &= (-5-9)\hat{i} - (10-3)\hat{j} + (6+1)\hat{k} \\ &= -14\hat{i} - 7\hat{j} + 7\hat{k} \end{aligned}$$

$$\begin{aligned} \vec{b} \times \vec{a} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 3 & 5 \\ 2 & -1 & 3 \end{vmatrix} = \begin{vmatrix} 3 & 5 \\ -1 & 3 \end{vmatrix} \hat{i} - \begin{vmatrix} 1 & 5 \\ 2 & 3 \end{vmatrix} \hat{j} + \begin{vmatrix} 1 & 3 \\ 2 & -1 \end{vmatrix} \hat{k} \\ &= (9+5)\hat{i} - (3-10)\hat{j} + (-1-6)\hat{k} \\ &= 14\hat{i} + 7\hat{j} - 7\hat{k} \end{aligned}$$

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Thm: For any vector $\vec{a} \in V_3$, $\vec{a} \times \vec{a} = \vec{0}$ and $\vec{a} \times \vec{0} = \vec{0}$

$$\text{Proof: } \vec{a} \times \vec{a} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ a_1 & a_2 & a_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ a_2 & a_3 \end{vmatrix} \hat{i} - \begin{vmatrix} a_1 & a_3 \\ a_1 & a_3 \end{vmatrix} \hat{j} + \begin{vmatrix} a_1 & a_2 \\ a_1 & a_2 \end{vmatrix} \hat{k} = 0\hat{i} + 0\hat{j} + 0\hat{k}$$

$$\vec{a} \times \vec{0} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ 0 & 0 & 0 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ 0 & 0 \end{vmatrix} \hat{i} - \begin{vmatrix} a_1 & a_3 \\ 0 & 0 \end{vmatrix} \hat{j} + \begin{vmatrix} a_1 & a_2 \\ 0 & 0 \end{vmatrix} \hat{k} = 0\hat{i} + 0\hat{j} + 0\hat{k}$$

We know that $\vec{a} \times \vec{b}$ is a vector. Can we determine anything about its direction relative to the directions of \vec{a} & \vec{b} ?

Let's compute $\vec{a} \cdot (\vec{a} \times \vec{b})$

$$\begin{aligned} \vec{a} \cdot (\vec{a} \times \vec{b}) &= (a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}) \cdot [(a_2 b_3 - a_3 b_2) \hat{i} - (a_1 b_3 - a_3 b_1) \hat{j} + (a_1 b_2 - a_2 b_1) \hat{k}] \\ &= a_1(a_2 b_3 - a_3 b_2) - a_2(a_1 b_3 - a_3 b_1) + a_3(a_1 b_2 - a_2 b_1) \\ &= a_1 a_2 b_3 - a_1 a_3 b_2 - a_1 a_2 b_3 + a_2 a_3 b_1 + a_1 a_3 b_2 - a_2 a_3 b_1 \\ &= 0 \end{aligned}$$

A similar thing happens for $\vec{b} \cdot (\vec{a} \times \vec{b})$

If the dot product of two vectors is zero then the vectors are orthogonal.

Thm: For any two vectors \vec{a} and \vec{b} in V_3 , $\vec{a} \times \vec{b}$ is orthogonal to both \vec{a} and \vec{b} .

We now know that $\vec{a} \times \vec{b}$ is orthogonal to \vec{a} and \vec{b} , but in which of the two possible directions does it point?

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The cross product obeys the "right hand rule":

Using your right hand

- 1) point your fingers in the direction of \vec{a}
- 2) "curl" your fingers into the direction of \vec{b}
- 3) your extended thumb will point in the direction of $\vec{a} \times \vec{b}$

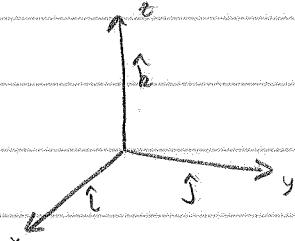


What does this rule say about the directions of $\vec{a} \times \vec{b}$ and $\vec{b} \times \vec{a}$?

$$\text{What is } \hat{i} \times \hat{j} = \hat{k} \quad \hat{j} \times \hat{i} = -\hat{k}$$

$$\hat{j} \times \hat{k} = \hat{i} \quad \hat{k} \times \hat{j} = -\hat{i}$$

$$\hat{k} \times \hat{i} = \hat{j} \quad \hat{i} \times \hat{k} = -\hat{j}$$



$$\text{Ex } (\hat{i} \times \hat{j}) \times \hat{j} = \hat{k} \times \hat{j} = -\hat{i} \quad \text{so}$$

$$\hat{i} \times (\hat{j} \times \hat{j}) = \hat{i} \times \vec{0} = \vec{0} \quad \text{so } ((\hat{i} \times \hat{j}) \times \hat{j}) \neq \hat{i} \times (\hat{j} \times \hat{j})$$

not associative

Thm: For any vectors $\vec{a}, \vec{b}, \vec{c} \in V_3$ and $d \in \mathbb{R}$

$$\text{i)} \quad \vec{a} \times \vec{b} = -(\vec{b} \times \vec{a})$$

$$\text{ii)} \quad (d\vec{a}) \times \vec{b} = d(\vec{a} \times \vec{b}) = \vec{a} \times (d\vec{b})$$

$$\text{iii)} \quad \vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$$

$$\text{iv)} \quad (\vec{a} + \vec{b}) \times \vec{c} = \vec{a} \times \vec{c} + \vec{b} \times \vec{c}$$

$$\text{v)} \quad \vec{a} \cdot (\vec{b} \times \vec{c}) = (\vec{a} \times \vec{b}) \cdot \vec{c}$$

$$\text{vi)} \quad \vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$$

The Cross Product

Recall that $\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$, $0 \leq \theta \leq \pi$ so

- $\vec{a} \cdot \vec{b}$ is as positive as possible when \vec{a} and \vec{b} point in the same direction
- $\vec{a} \cdot \vec{b}$ is zero if \vec{a} and \vec{b} are orthogonal
- as negative as possible when \vec{a} and \vec{b} point in opposite directions

Now examine $\|\vec{a} \times \vec{b}\|$.

$$\begin{aligned}
 \|\vec{a} \times \vec{b}\|^2 &= (a_2 b_3 - a_3 b_2)^2 + (a_3 b_1 - a_1 b_3)^2 + (a_1 b_2 - a_2 b_1)^2 \\
 &= (a_1^2 + a_2^2 + a_3^2)(b_1^2 + b_2^2 + b_3^2) - (a_1 b_1 + a_2 b_2 + a_3 b_3)^2 \quad [\text{See text}] \\
 &= \|\vec{a}\|^2 \|\vec{b}\|^2 - (\vec{a} \cdot \vec{b})^2 \\
 &= \|\vec{a}\|^2 \|\vec{b}\|^2 - \|\vec{a}\|^2 \|\vec{b}\|^2 \cos^2 \theta \\
 &= \|\vec{a}\|^2 \|\vec{b}\|^2 (1 - \cos^2 \theta) \\
 &= \|\vec{a}\|^2 \|\vec{b}\|^2 \sin^2 \theta
 \end{aligned}$$

$$\therefore \|\vec{a} \times \vec{b}\| = \|\vec{a}\| \|\vec{b}\| \sin \theta$$

Thm: For nonzero vectors \vec{a} and \vec{b} in V_3 , if θ is the angle ($0 \leq \theta \leq \pi$) between \vec{a} and \vec{b} then

$$\|\vec{a} \times \vec{b}\| = \|\vec{a}\| \|\vec{b}\| \sin \theta$$

$$\text{and } \vec{a} \times \vec{b} = \|\vec{a}\| \|\vec{b}\| \sin \theta \hat{n}$$

where \hat{n} is a unit vector whose direction is determined by the right hand rule.

Corollary: Two nonzero vectors \vec{a} and \vec{b} in V_3 are parallel if and only if $\vec{a} \times \vec{b} = \vec{0}$